

Table of Contents

I. Robotics: Industrial Robots, Microrobotics

Conception of Arm of Medical Robot Dedicated to Application of Minimally Invasive Surgery R. Trochimczuk	3
Delta Robot Design L. Březina, M. Holub, L. Cintula and J. Kovar	9
Mathematical Model of the Servo Drive with Friction Wheals. Simulations and Real Object Examination Results L. Fraczak	15
Mechatronic Design of a Parallel Robot for Milling M. Petko and G. Karpel	21
Mechatronic System for the Production of Highly Secured Documents T. Samborski and A. Zbrowski	27
Redundantly Actuated 3RRR Parallel Planar Manipulator - Numerical Analyses of its Dynamics Sensitivity on Modifications of its Platforms Inertia Parameters K. Lipiński	33
Remote Advanced Supervision and Diagnostics of Robotized Welding Cell Z. Pilat, J. Zieliński and M. Słowikowski	39
Robot Control System for Stereotactic Surgery M. Sibielak, W. Rączka, J. Konieczny, M. Moskała and M. Krupa	45
Solution for Inverse Kinematics of 5 DOF Serial Link MCM Machine P. Kozioł, K. Kukliński, A. Wolniakowski and K. Miatliuk	53
The Simulator for Teaching how to Drive a Car for People with Disabilities A. Dymarek, T. Dzitkowski, K. Herbuś, G. Kost and P. Ociepka	59

II. Mobile Robots

Analysis of the Kinematics of an Eight-Wheeled Mobile Platform M. Stania	67
Behavior Based Complete Coverage Task of Unknown Area by an Autonomous Mobile Robot SCORPION with Static Obstacles in Environment M. Dąbkowski, P. Skrzek and G. Redlarski	73
Concept of Locomotion Mobile Undercarriage Structure Control for the Path Tracking E. Miková, F. Trebuňa and M. Kelemen	79
Fuel Cells for Autonomous Underwater Vehicles G. Grzeczka and A. Polak	84
HILS for the Design of Three-Wheeled Mobile Platform Motion Surveillance System with a Use of Energy Performance Index K.J. Kaliński and C. Buchholz	90
Mechatronics Systems of Autonomous Transport Vehicle M. Stania	96
Mobile Sensor Motion Planning for Identification of a Contamination Source Using Iterative Dynamic Programming P. Ziemniak	102
Neural Network Based Reactive Navigation for Mobile Robot in Dynamic Environment J. Krejsa, S. Věchet and T. Ripel	108
Path Planning with the Use of Artificial Ant Colony Algorithm S. Věchet and T. Ripel	114
Pneumatic Robot for Monitoring Hazardous Environments of Coal Mines L. Kaspryczak, S. Trenczek and M. Cader	120

Polymer Fuel Cells in Underwater Platforms	126
G. Grzeczka	
Structures of the Omnidirectional Robots with Swedish Wheels	132
M.O. Tătar, C. Cirebea and D. Mândru	
Using River Formation Dynamics Algorithm in Mobile Robot Navigation	138
G. Redlarski, A. Pałkowski and M. Dąbkowski	
Vision Analysis of a Biomimetic Water Vehicle Propeller	144
A. Sioma and W. Lepiarz	

III. Unmanned Aerial Vehicles

3D Attitude Estimation in Indoor Environments with a Complementary Filter for the Special Orthogonal Group SO(3)	153
M. Kmiecik and K. Sibilski	
A Stereovision System for Real Time Obstacle Avoidance by Unmanned Aerial Vehicle	159
J. Cieśluk and Z. Gosiewski	
Algorithms of Measurement System for a Micro UAV	165
G. Kopecki, A. Tomczyk and P. Rzucidło	
Application of Unfalsified Control Theory in Controlling MAV	171
A. Wolniakowski and A. Mystkowski	
Autonomous Flight in the Canyons of Streets on the Basis of Information Derived from the Vision System	176
C. Kownacki and M. Bogdan	
Base Station for Monitoring of Unmanned Aerial Vehicle Flight	182
M. Słowik and Z. Gosiewski	
Development of a Model for the Intake Channel within a MRCA Turbine Engine in Order to Analyze Intake Vortex Phenomena	188
A. Kozakiewicz	
Flight Loads of Mini UAV	194
A. Majka	
Hybrid Electroactive Wings Morphing for Aeronautic Applications	200
M. Chinaud, J. Scheller, J.F. Rouchon, E. Duhamon and M. Braza	
Modeling, Simulation and Control of Microelectromechanical Flying Insect	206
K. Sibilski and A. Żyluk	
Modelling of Dynamic and Control of Six-Rotor Autonomous Unmanned Aerial Vehicle	220
D. Ołdziej and Z. Gosiewski	
Optimization of Lift Force of Mini Quadrotor Helicopter by Changing of Gap Size between Rotors	226
D. Aleksandrov and I. Penkov	
Preliminary UAV Autopilot Integration and In-Flight Testing	232
L. Ambroziak and Z. Gosiewski	
Simulation Method of UAV Avionics System Designing	238
K. Wojtowicz, W. Sobieraj and B. Brzozowski	
Testing Some Alpha-Models of Turbulence on Wing Profiles	243
M.A. Moreno, B. González, V. Enríquez, F.A. Déniz, R. Aguasca and G. Winter	
The Analysis of the Influence of the Design Parameters on the Performance Characteristics of a Mini UAV	248
A. Majka	
UAV Autonomous Formation Flight Experiment with Virtual Leader Control Structure	254
Z. Gosiewski and L. Ambroziak	
UAV Avionics System Software Development Using Simulation Method	260
B. Brzozowski, W. Sobieraj and K. Wojtowicz	
Unmanned Air Vehicle Research Simulator - Prototyping and Testing of Control and Navigation Systems	266
P. Rzucidło	

IV. Teleoperation, Telerobotics, Teleoperated Semi-Autonomous Systems

Telemanipulator Control with Varying Camera Position

L. Podśdkowski, P. Wróblewski and M. Zawierucha

275

V. Sensors and Actuators in Mechatronics

Characteristics of an Experimental MSMA-Based Actuator

S. Flaga, I. Oprzędkiewicz and B. Sapiński

283

Cleaning System for Automated Optical Inspection of Heads of Bearing Rollers

A. Zbrowski

289

Controlled Conditioning System for the Electromagnetic Generator Supporting an MR Damper: Prototyping and Testing

M. Rosół, B. Sapiński and M. Knapik

295

Determination of Energy Parameters of Impact Cylinders

A. Zbrowski and W. Józwik

301

Elastic Interdigital Transducers for Lamb Wave Generations

M. Mańska, A. Martowicz, M. Rosiek and T. Uhl

307

Haptic Devices Based on Planar Stepping Motors Introductory Concept

T. Huścio and W. Kołodziejczyk

313

Homogeneous Flow of Hydraulic Fluid Retaining Gap

L. Ułanowicz

318

Investigation of Multifunctional Actuators on an Air-Cushion

K. Vaitasius, D. Pauliukaitis and E. Kibirkštis

324

Investigation of Oscillations of the Piezoelectric Actuator with Two-Directional Polarization

R. Lučinskis, D. Mažeika and R. Bansevičius

328

Laboratory Stand of an Electromagnetic Multi-Coil Launcher for Micro Aerial Vehicles

M. Kondratuk and Z. Gosiewski

334

Magnetic Field and Circuit Parameters in an Electromagnetic Generator Supporting a Rotary MR Damper

B. Sapiński

340

Magnetic Thrust Bearing for the ORC High – Speed Microturbine

Z. Kozanecki and J. Łagodziński

348

Mathematical Analysis and Investigation Results of the Bearingless Electric Motor with Permanent Magnets

M. Henzel

354

Measurement of Human Locomotion: Evaluation of Low-Cost KINECT and SHIMMER Sensors

H. Loose and K. Orlowski

360

Mechatronic System for Impact Tests for Aero Structures

A. Zbrowski and A. Majcher

366

Modelling of the Planar Aerostatic Two-Coordinate Relative Bases

T. Huścio and F. Siemieniako

372

New Method of Measurements of Magnetic Characteristics in Two Perpendicular Axis of Amorphous Ribbon

P. Frydrych, R. Szewczyk, J. Salach and K. Trzcinka

378

Numerical and Experimental Testing of Bearingless Induction Motor

Z. Gosiewski, M. Henzel, K. Falkowski and M. Źokowski

382

Possibilities of Application of Amorphous $\text{Fe}_{77}\text{Cr}_2\text{B}_{16}\text{Si}_5$ Alloys in Different States of Thermal Relaxation as Magnetic Tensile Force Sensors

J. Salach, R. Szewczyk, A. Bieńkowski and D. Jackiewicz

388

Rubber Structural Coupon Behaviour Study under Pressure Impulse

P. Baranowski, J. Malachowski, L. Mazurkiewicz and K. Damaziak

394

Second-Order Model of the Radial Passive Magnetic Bearing with Halbach's Array

K. Falkowski

400

Simulation Model of an Electromagnetic Multi-Coil Launcher for Micro Aerial Vehicles	406
M. Kondratuk and Z. Gosiewski	
The Temperature Influence on the Linear Actuator Static Parameters	412
A. Waindok and B. Tomczuk	

VI. Control of Mechatronic Systems

Load Control in Upper Limb Exercising	421
R. Maskvytis, V. Eidukynas, I. Tiknevičienė and R.T. Toločka	
Active Synthesis of Discrete Systems as a Tool for Reduction Vibration	427
A. Dymarek and T. Dzitkowski	
Active Vibration Control Method for Space Mechanical Structure with Piezostacks	433
A.P. Koszewnik	
Balance Platform Model Parameter Identification	439
A. Nawrocka and A. Kot	
Cam_Gate System in Product Quality Control, Optimal Selection of Inspecting-Sorting Automatic Machines	445
K. Łasiński	
Commissioning and Control of the AMB Supported 3.5 kW Laboratory Gas Blower Prototype	451
R.P. Jastrzębski, A. Smirnov, K. Hynynen, J. Nerg, J. Sopanen, T. Lindh, J. Heikkinen and O. Pyrhönen	
Control Driven Advances in Smart Rotating Machinery	457
J.T. Sawicki	
Control System of a Manipulation Mechanism for Acoustical Measurement in Anechoic Chamber	467
J. Mężyk, A. Flach and A. Zbrowski	
Diversity of Servo-Constraint Problems for Underactuated Mechanical Systems: A Case Study Illustration	473
W. Blajer, R. Seifried and K. Kołodziejczyk	
Energy Dissipation of Synchronized Switch Damping with Piezoceramics Using Negative Capacitance	483
M. Neubauer, X. Han and J. Wallaschek	
Energy Parameter Control System of Strength Machine for Material Tests under Cyclic Bending and Torsion	489
L. Kasprzyczak, E. Macha and Z. Marciniak	
Force Controllers for AMB Systems with Position and Current Feedback	495
R.P. Jastrzębski, A. Smirnov and O. Pyrhönen	
Genetic Fuzzy Approach for Designing a Gain Scheduling Anti-Sway Crane Control System	501
J. Smoczek	
Hardware in the Loop Test Rig for Development of Control Algorithms for Electric Vehicles	507
F. Quantmeyer and X.B. Liu-Henke	
Influence of Bias Current Value on Properties of Active Magnetic Bearing	513
B. Tomczuk, D. Wajnert and J. Zimon	
Mathematical Models of Control Systems of Angular Speed of Steam Turbines for Diagnostic Tests of Automatic and Mechatronic Devices	519
G. Redlarski, J. Piechocki and M. Dąbkowski	
Model Predictive Control for Lateral Position of Endless Metal Belts	525
S. Grosswindhager, K. Schulmeister and M. Kozek	
Modeling of a Battery Electric Vehicle (BEV) for Efficient Model-Based Design	533
R. Buchta and X.B. Liu-Henke	
Modelling of Ship's Heeling and Rolling for the Purpose of Gantry Control Improvement in the Course of Cargo Handling Operations in Sea Ports	539
P. Krata, J. Szpytko and A. Weinrit	
Monitoring and Diagnostics of the Rotating System with an Active Magnetic Bearing	547
M. Gizelska, D. Kozanecka and Z. Kozanecki	

Multi-Objective Optimization of the Electromagnetic Actuator Control S. Pecolt and T. Krzyżynski	553
Non-Collision Path Planning of a Payload in Crane Operating Space J. Smoczek, J. Szpytko and P. Hyla	559
Novel Concepts and Criteria for Design Optimization of Controlled Mechanical Systems P. Kiriazov	565
Robust Optimal Control of MAV Based on Linear-Time Varying Decoupled Model Dynamics A. Mystkowski	571
Speed/Position Sensorless Control of Two-Phase Induction Motor Drive System Using Virtual Injection Method B. Dobrucky, S. Kascak and M. Prazenica	577
Synthesis of New Mechatronic Systems by Inverse Algorithm J. Viba, S. Cifanskis and I. Tipans	583
The Anti-Sway Crane Control System with Using Dynamic Vision System J. Smoczek, J. Szpytko and P. Hyla	589
The Concept of an Interactive Device for Children's Lower Limbs Rehabilitation I. Chuchnowska and A. Sękala	594
The Control System for a Vibration Exciter J. Konieczny, M. Sibielak and W. Rączka	600
Using CompactRIO to Build a Virtual Driver of Hybrid Wheeled Vehicle G. Kost and A. Nierychłok	606

VII. Analysis of Vibration and Deformation

A Method for Shaping the Dynamic Characteristics of Vibration Isolation Systems I. Maciejewski	615
A Simplified Model of 3-D Pipe System Conveying Flowing Liquid C. Orlikowski and R. Hein	621
Development and Validation of Numerical Model for Predicting Electromagnetic Expansion of Composite Rings J. Janiszewski and R. Panowicz	627
Dynamic Characteristics of a Piezoelectric Transducer with Structural Damping M. Płaczek	633
Harmonic Analysis of Self-Excited Acoustical System for Stress Changes Measurement in Compressed Steel Structural Section J. Kwaśniewski, I. Dominik, K. Lalik and R. Szymański	639
Investigation of Bodies Vibrations with Elastomeric Elements I. Tipans, M. Eiduks, J. Viba, M. Grishchenko and V. Grzibovska	645
Investigation of Dynamic Processes in Ball Bearings with Defects M. Bogdevičius and V. Skrickij	651
Mechanical Subsystem as Implementation of Active Reduction of Vibration K. Białas	657
Modeling of a Nonlinear Vibration-Based Energy Harvesting System as a Duffing Oscillator H. Westermann, M. Neubauer and J. Wallaschek	663
Modelling of Geared Multi-Rotor System C. Orlikowski and R. Hein	669
Optimal Design of System of Cross-Beams G. Aryassov and S. Zhigailov	675
The Detection of Nut Driver's Optimal Working Regimes Taking into Account Power Consumption and Assembly Time during Fixed Threaded Joints Assembly I. Grinevich and N. Mozga	681
The Optimal Spindle Speed Map for Reduction of Chatter Vibration during Milling of Bow Thruster Blade K.J. Kaliński, M.R. Mazur and M.A. Galewski	686
The Parametric Optimization of Structure Mass of Swept Wing in Compliance to Stiffness and Strength Boundary Conditions S. Kachel	692

Vibration Analysis of Mechanical Systems with the Discrete-Continuous Distribution of Parameters

K. Białas and A. Sękala

698