Table of Contents

Preface

Chapter 1: Control Systems

J. Brzózka	3
Fuzzy Control of Reactant Supply System in PEM Fuel Cell S. Hożyń and B. Żak	11
Architecture of the Control System of an Unmanned Surface Vehicle in the Process of Harbour Protection Z. Kitowski	20
Optimal Control of the Searching and Tracking Head (STH) for Self Propelled Anti	20
Aircraft Vehicle Z. Koruba	27
Virtual Driver of Hybrid Wheeled Vehicle G. Kost and A. Nierychlok	39
Supervisory Controller of the Ship Propulsion Plant J. Kruszewski	46
The Multistage Positional Game of Marine Objects with Different Degree of Cooperation J. Lisowski	56
The Optimal and Safe Ship Trajectories for Different Forms of Neural State Constraints J. Lisowski	64
Safe Ship's Control in a Fuzzy Environment Using a Genetic Algorithm M.M. Seghir	70
Possibility of Automation of a Mobile Biodiesel Production Plant A. Piętak, S. Wierzbicki and K. Duda	76
The Influence of Fitness Function on Quality of Neuro-Controllers Produced with Assembler Encoding	
T. Praczyk	89
Analysis of Interactions between Pilot-Operator and Advanced Flight Control System P. Rzucidło and P. Chudy	101
Decision-Making Processes in Transport Telematic Systems Exploitations M. Siergiejczyk	109
Comparison of Centralized, Dispersed and Hybrid Multiagent Control Systems of Underwater Vehicles Team	
P. Szymak	114
Chapter 2: Robotics	
Power Distribution in Propulsion System of Semiautonomous Underwater Vehicle J. Garus	125
Map Building System for Unmanned Ground Vehicle A. Typiak and M. Gnatowski	131
Six-Legged Walking Robot for Inspection Tasks S. Krenich and M. Urbanczyk	137
Hydroacoustic Multi-Sensor for Positioning Underwater Robots K. Listewnik	145
Application of the Maggi Equations to Mathematical Modeling of a Robotic Underwater Vehicle as an Object with Superimposed Non-Holonomic Constraints Treated as Control Laws	
E. Ladyżyńska-Kozdraś	152
Conception of Research on Bionic Underwater Vehicle with Undulating Propulsion P. Szymak, M. Morawski and M. Malec	160

Neural Controlling of Remotely Operated Underwater Vehicle A. Żak	168
Chapter 3: Diagnostics	
Data Dimension Reduction and Visualization with Application to Multi-Dimensional Gearbox Diagnostics Data: Comparison of Several Methods A. Bartkowiak and R. Zimroz	177
Conception and Practical Application of a Measuring Device for Energetic Parameters Measurement of a Mechatronic Object A. Cwalina and M. Zacharewicz	185
Investigations of the Vibroacoustic Signals Sensitivity to Mechanical Defects Not Recognised by the OBD System in Diesel Engines Z. Dabrowski and M. Zawisza	194
Modelling of the Toothed Gear Operations with the Application of the Analysis of the Gear Sliding Mesh Velocity Changes J. Dziurdź	200
FPGA – ARM Heterogeneous System for High Speed Signal Analysis E. Jamro, M. Wielgosz, S. Bieniasz and W. Cioch	207
Diagnostic-Oriented Vibroacoustic Model of the Reciprocating Engine I. Komorska	214
Measuring and Recording Systems Used in Flight Tests of Aircraft M. Nowakowski	222
Control Measurements at the Manufacturing of Metallic Products W. Tarczyński and R. Kopka Lightification of Destructive Processes Affecting Hydraulic Servementarium of the	232
Identification of Destructive Processes Affecting Hydraulic Servomechanisms of the Aircraft Control Assist System L. Ułanowicz	238
Application of Adaptive Filtering for Weak Impulsive Signal Recovery for Bearings Local Damage Detection in Complex Mining Mechanical Systems Working under Condition of Varying Load R. Zimroz and W. Bartelmus	250
Chapter 4: Mechatronic Systems	
Glued Functions - Based Assessment of Interpolation Accuracy of Self-Ignition Engine Real Indicator Diagram	2(1
A. Ambrozik Modelling and the Elements of Controlled Dynamics of the Anti-Aircraft Missile Launcher Based Onboard the Warship	261
Z. Dziopa and Z. Koruba Determination of Suction Forces and Moment on Parallel Manoeuvring Vessels for a Future Control System	269
W. Gierusz and A. Waszkiel Ship Shock Modeling of Underwater Explosion A. Grządziela	281 288
Implementation of Integrated Thermal and Humidification Subsystems of 6 kW PEM Fuel Cell System G. Grzeczka	
Modelling of the Ship Structural Ballistic Shields from the 10GHMBA Steel W. Jurczak and L. Kyzioł	297 303
The Dynamics of the Controlled Observation and Tracking Head Located on a Moving Vehicle	
I. Krzysztofik Model of Propeller for the Precision Control of Marine Vehicle J. Małecki	313 323
Simple Identification of Fractional Differential Equation W. Mitkowski and A. Obrączka	331

The Investigation of Turbine Engine in Aspect of Output Torque Control B. Pojawa	339
Dual-Input Current-Mode Gate Using for Digital Signal Processing in Mechatronic Systems M. Rajewska and M. Walkowiak	349
The Methods of Evaluation the Mobility of Off - Road Vehicles P. Sprawka	355
Digital Receiving of OQPSK Signals Dedicated for Maritime Mechatronic Systems R. Studański	366